AFAS – adaptive fast approximate simulation for non-linear model reduction

Shahkar Ahmad Nahvi*, Mashuq-un-Nabi and S. Janardhanan

Department of Electrical Engineering, Indian Institute of Technology, New Delhi, 110016, India E-mail: s.a.nahvi@gmail.com E-mail: mnabi@ee.iitd.ac.in E-mail: janas@ee.iitd.ac.in

*Corresponding author

Abstract: In this work, we examine the problem of selecting linearisation points for trajectory piecewise linear (TPWL) approximation of non-linear dynamical systems. Linearisation point selection is a crucial step in the TPWL process, the quality and complexity of the approximation rests on it. In contrast to the popular approaches wherein linearisations are done at constant, pre-selected Euclidean distances in the state-space, we propose a new and simple error measure that helps in assessing the linearisation point requirement at different points on the non-linear system trajectory. Based on this error measure a new scheme to simulate the non-linear system, create linearisations at viable points and obtain a better TPWL approximation is presented. Finally, we substantiate our observations and propositions by detailed numerical tests on two non-linear circuits.

Keywords: large dynamical systems; model order reduction; MOR; non-linear systems; simulation; approximate simulation; modelling; trajectory piecewise linear; TPWL; linearisation point selection; trajectory sampling; error analysis.

Reference to this paper should be made as follows; Nahvi, S.A., Nabi, M.u. and Janardhanan, S. (2013) 'AFAS — adaptive fast approximate simulation for non-linear model reduction', Int. J. Modelling, Identification and Control, Vol. 19, No. 2, pp.113–124.

Biographical notes: Shahkar Ahmad Nahvi received his MTech in Power System and Drives from Electrical Engineering Department, Aligarh Muslim University, Aligarh, India in 2005 and is currently pursuing his PhD in Electrical Engineering from Department of Electrical Engineering, Indian Institute of Technology, Delhi, India. He is a faculty member with College of Engineering, Islamic University of Science and Technology, Pulwama, J&K, India. His research interests include model order reduction of non-linear dynamical systems and optimal control using reduced-order models.

Mashuq-un-Nabi received his PhD in Electrical Engineering from Indian Institute of Technology, Bombay, India in 2004. He is currently working as an Assistant Professor in the Department of Electrical Engineering, Indian Institute of Technology, Delhi, India. His research interests include model order reduction of non-linear and parametric systems, computational algorithms for modelling and simulation of distributed systems and finite element modelling of electromagnetic and coupled systems.

S. Janardhanan received his PhD in Systems and Control Engineering from Indian Institute of Technology, Bombay, India in 2006. He is currently working as an Assistant Professor in the Department of Electrical Engineering, Indian Institute of Technology, Delhi, India. His research interests include discrete time systems, model order reduction, sliding mode control and robust control.

This paper is a revised and expanded version of a paper entitled 'Adaptive sampling of nonlinear system trajectory for model order reduction' presented at International Conference on Modelling, Identification and Control, Wuhan, China, 24–26 June 2012.